

# GPGPU Programming & Erlang

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# What is GPGPU Programming?

- Using the graphics processor for non-graphical programming
- Writing algorithms for the GPU instead of the host processor

# Why?

- Ridiculous amount of parallelism
- Very high throughput
- Economical

# Common Uses

- Medical Imaging
- Oil & Gas Exploration
- Data Mining
- Algorithmic Trading

# Moving Into The Mainstream

- **PacketShader: A GPU-Accelerated software router** (Han, Jang, Park & Moon)
- **SSLShader: Cheap SSL Acceleration with Commodity Processors** (Jang, Han, Han, Moon & Park)
- **Mars: A MapReduce Framework on Graphics Processors** (He, Fang, Govindaraju, Luo & Tuyong)
- **Augmenting Operating Systems With the GPU** (Sun & Ricci)

# GPGPU & You

- Sorting
- Searching
- Reductions: average, median, etc
- Transforms: uniquifying, permutations

# GPGPU & You

- Extrema: min/max
- Prefix scans & sums
- Set operations
- High quality random numbers

# What is CUDA?

- GPGPU framework for NVIDIA GPUs
- Extends programmable shaders
- Extensions to C
- Runtime framework

# Why Use CUDA?

- Wide array of cards
- Shallow learning curve
- Lots of resources

# GeForce 210

CPU: 16 Cores

Memory: 1 GB

Cost: \$44.99



# GeForce GT 240

CPU: 96 Cores

Memory: 1 GB

Cost: \$79.99



# GeForce GTS 450

CPU: 192 Cores

Memory: 1 GB

Cost: \$149.99



# GeForce GTX 460

CPU: 336 Cores

Memory: 1 GB

Cost: \$230 (approx.)



# GeForce GTX 470

CPU: 448 Cores

Memory: 1.2 GB

Cost: \$280 (approx.)



# GeForce GTX 480

CPU: 480 Cores

Memory: 1.5 GB

Cost: \$425 (approx.)



# GeForce GTX 580

CPU: 512 Cores

Memory: 1.5 GB

Cost: \$499+ (approx.)



# GeForce GTX 590

CPU: 1024 Cores

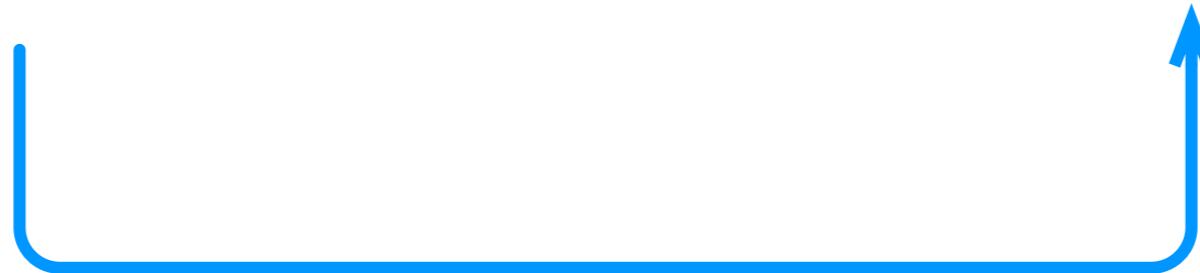
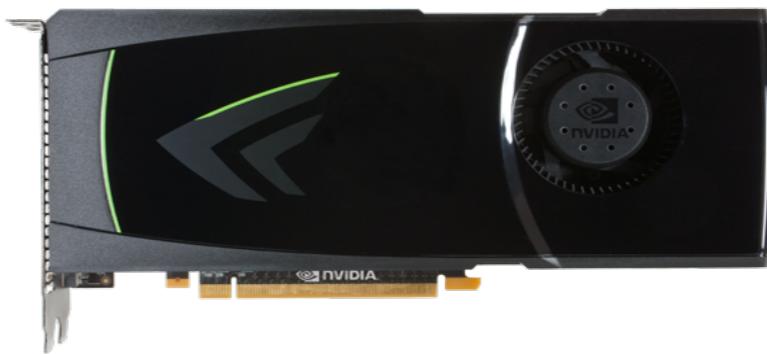
Memory: 3.5 GB

Cost: \$699+ (approx.)



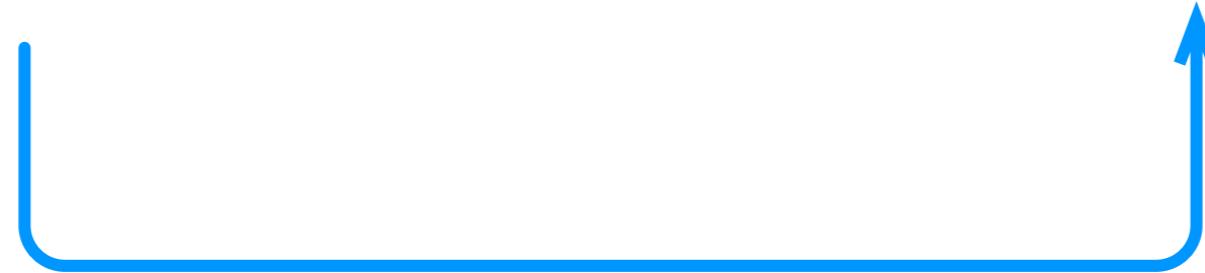
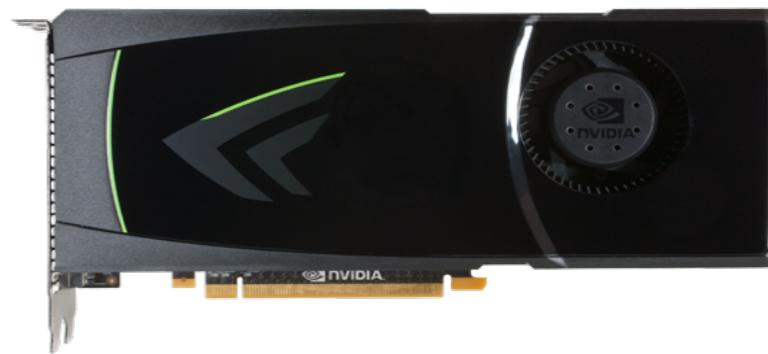
# How CUDA Works

# Write Data



Runs at PCIe speeds  
~ 2.5Gbps

# Execute Code

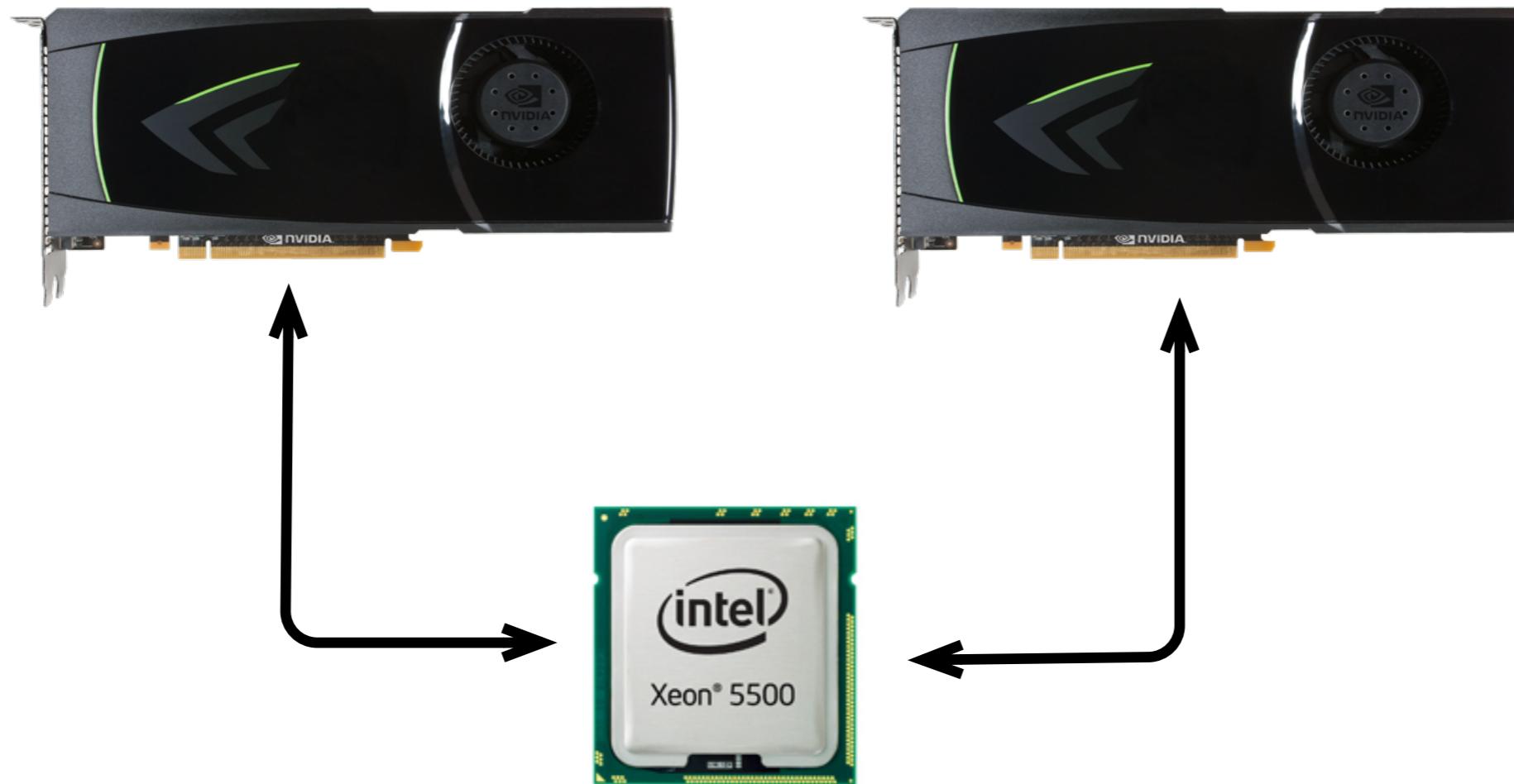


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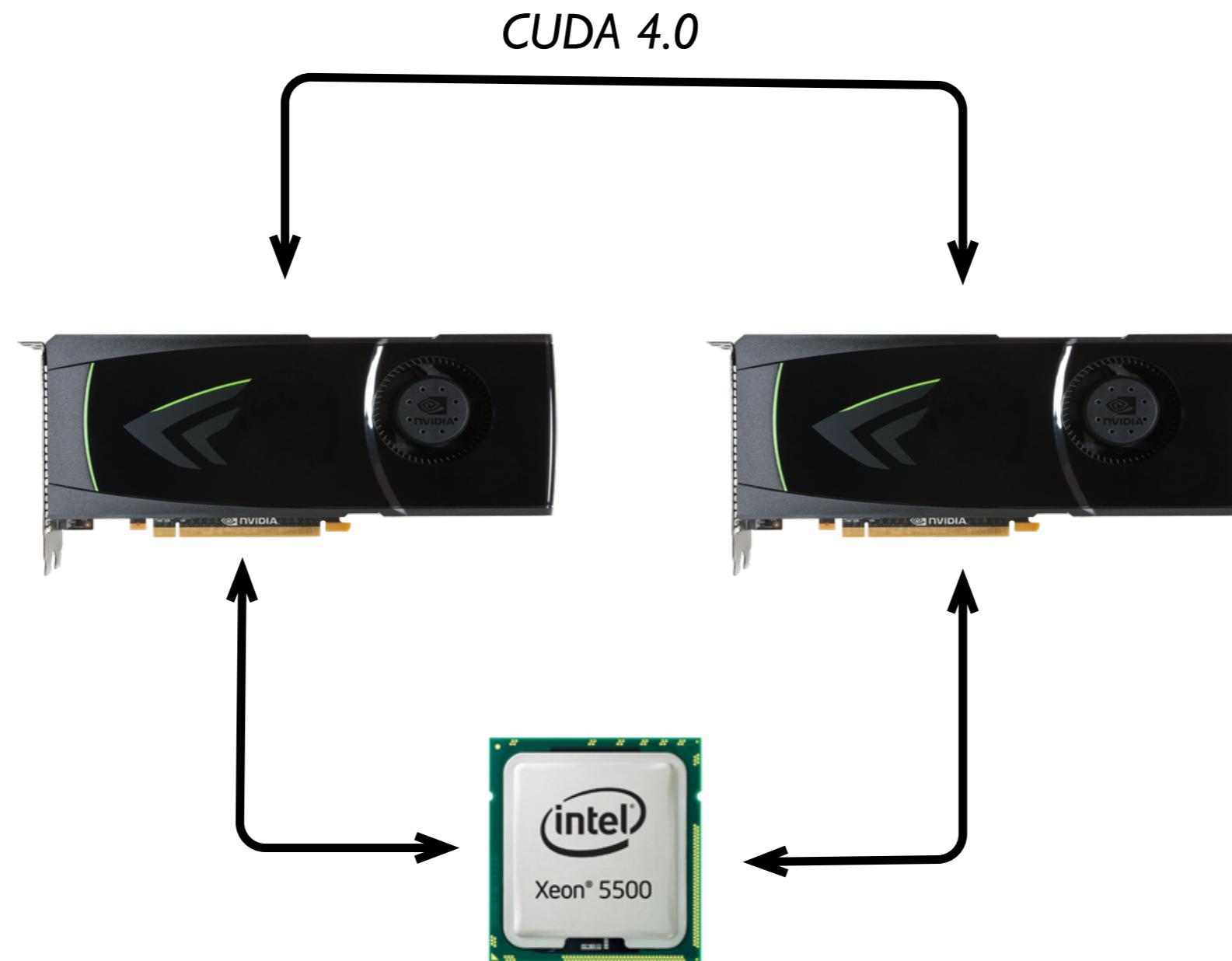
# Read Result



# Multiple GPUs



# Multiple GPUs



# (Brief) CUDA Overview

```
#include <iostream>

#include "cuda.h"

__global__ void add(int a, int b, int *c) {
    *c = a + b;
}

int main() {
    int c;
    int *dev_c;
    add<<1, 1>>(100, 100, dev_c);
    cudaMemcpy(&c, dev_c, sizeof(int), cudaMemcpyDeviceToHost);
    printf("100 + 100 = %d\n", c);
    cudaFree(dev_c);

    return 0;
}
```

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    cudaFree(dev_c);

    return 0;
}
```

# Summing Vectors

$$\begin{array}{c} 37 \\ + \quad 99 \\ \hline \end{array} = \boxed{\text{??}} \quad \begin{array}{c} 86 \\ + \quad 45 \\ \hline \end{array} = \boxed{\text{??}} \quad \begin{array}{c} 77 \\ + \quad 67 \\ \hline \end{array} = \boxed{\text{??}} \quad \begin{array}{c} 92 \\ + \quad 68 \\ \hline \end{array} = \boxed{\text{??}}$$

# Summing Vectors

```
__global__ void add(int *first, int *second, int *result) {  
    int thread_id = blockIdx.x;  
    result[thread_id] = first[thread_id] + second[thread_id];  
}
```

# Summing Vectors

```
int main() {
    /* Declare data and result vectors */
    int first[100], second[100], result[100];
    int *dev_first, *dev_second, *dev_result;

    /* Alloc work space on device */
    cudaMalloc( (void **) &dev_first, 100 * sizeof(int));
    cudaMalloc( (void **) &dev_second, 100 * sizeof(int));
    cudaMalloc( (void **) &dev_result, 100 * sizeof(int));

    /* Populate vectors on host */
    for (int i = 0; i < 100; i++) {
        first[i] = i;
        second[i] = i * 2;
    }

    /* Move data to device */
    cudaMemcpy(dev_first, first, 100 * sizeof(int), cudaMemcpyHostToDevice);
    cudaMemcpy(dev_second, second, 100 * sizeof(int), cudaMemcpyHostToDevice);

    add<<25, 1>>(dev_first, dev_second, dev_result);

    /* Copy results back to host */
    cudaMemcpy(result, dev_result, 100 * sizeof(int), cudaMemcpyDeviceToHost);
    cudaFree(dev_first);
    cudaFree(dev_second);
    cudaFree(dev_thirst);
}
```

# CUDA

## Pros & Cons

- Uses a well-known language (C)
- Extends common idioms to the GPU
- Verbose, Error prone
- Complete control over computing environment
- Low-level

# Introducing Thrust

- C++ framework for GPU computing
- STL-like algorithms for common CUDA operations
- Reduces verbosity & errors
- Included in CUDA 4.0

# Summing Vectors

```
int main() {  
  
    thrust::device_vector<int> dev_first(100);  
    thrust::device_vector<int> dev_second(100);  
    thrust::device_vector<int> dev_result(100);  
    std::vector<int> result(100);  
  
    // Fill device arrays with data  
    thrust::sequence(dev_first.begin(), dev_first.end(), 1);  
    thrust::sequence(dev_second.begin(), dev_second.end(), 1);  
  
    thrust::add<int> op;  
  
    // Add arrays  
    thrust::transform(dev_first.begin(), dev_first.end(), dev_second.begin(),  
                    dev_result.begin(), op);  
    // Copy results to host array  
    thrust::copy(dev_result.begin(), dev_result.end(), result.begin());  
}
```

# pteracuda

# What is pteracuda?

- Experiment to integrate CUDA & Erlang
- Accelerate slow Erlang operations
- Built on CUDA 4.0 RCI

# Main Concepts

- Context - Environment for CUDA operations

```
{ok, Ctx} = pteracuda_context:new().  
pteracuda_context:destroy(Ctx).
```

# Main Concepts

- Buffer - Typed list of data
  - Integer
  - Float
  - String \*\*\*

```
{ok, Buf} = pteracuda_buffer:new(integer).  
pteracuda_buffer:destroy(Buf).
```

# Working With Buffers

- Write
- Read
- Insert
- Delete
- Clear

# CUDA Accelerated Operations

- Sort
- Contains (binary search)
- Intersection
- Min/Max

# **DEMO**

[https://github.com/kevsmith/  
pteracuda](https://github.com/kevsmith/pteracuda)